

1. $q_1 = q > 0, q_2 = -q, Q > 0, |AB| = a, h$

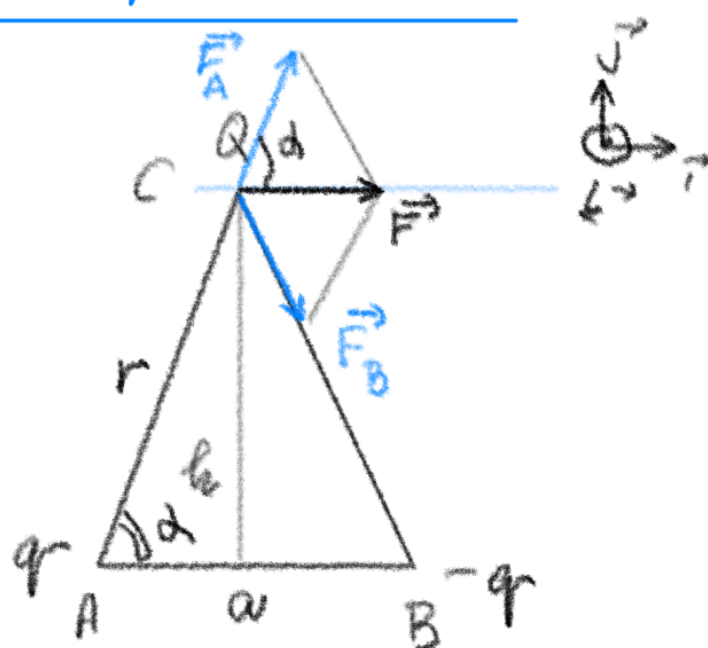
F_j

$$F_A = F_B = \frac{1}{4\pi\epsilon_0} \frac{Qq}{r^2}$$

$$\vec{F} = \vec{F}_A + \vec{F}_B$$

$$F_{Ay} + F_{By} = 0$$

$$F = F_{Ax} + F_{Bx} = 2F_{Ax}$$



$$\frac{a}{2} = r \cos \alpha \Rightarrow r^2 = \left(\frac{a}{2 \cos \alpha} \right)^2$$

$$F_{Ax} = F_{Bx} = F_A \cos \alpha = \frac{1}{4\pi\epsilon_0} \frac{Qq}{a^2} 4 \cos^2 \alpha \cos \alpha = \frac{Qq}{\pi\epsilon_0 a^2} \cos^3 \alpha$$

$$\cos \alpha = \frac{a}{2r} = \frac{a}{2\sqrt{\frac{a^2}{4} + h^2}} = \frac{a}{\sqrt{a^2 + 4h^2}}$$

$$F = 2 \frac{Qq}{\pi\epsilon_0 a^2} \cdot \frac{a^3}{(\sqrt{a^2 + 4h^2})^3} = \frac{2Qq}{\pi\epsilon_0 a^2} \frac{1}{(1 + 4h^2/a^2)^{3/2}}$$

2. C_j

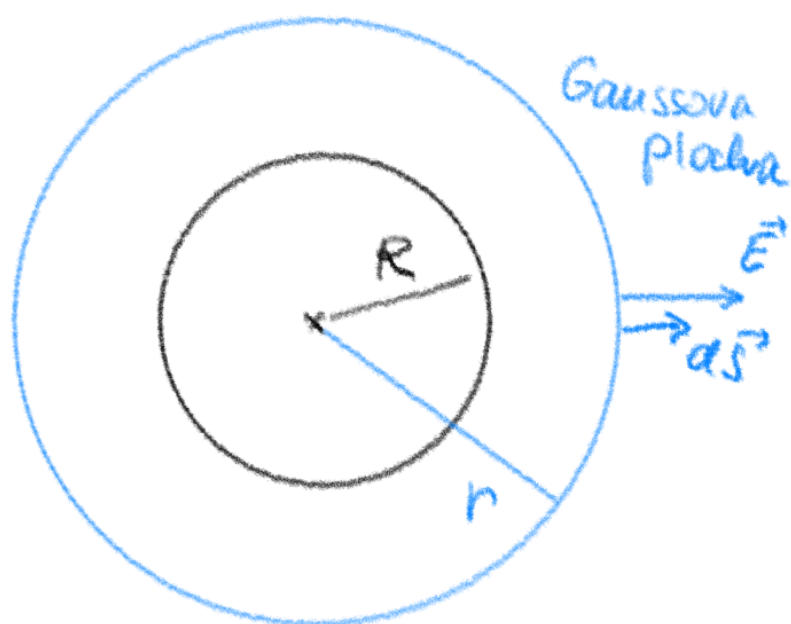
$$C = \frac{Q}{\varphi}$$

$$\varphi = - \int_{\infty}^R E dr$$

$$\oint_S \vec{E} \cdot d\vec{S} = \frac{Q}{\epsilon_0}$$

$$\vec{E} \parallel d\vec{S} \Rightarrow \vec{E} \cdot d\vec{S} = E dS$$

$$\oint_S \vec{E} \cdot d\vec{S} = \oint_S E dS = E \oint_S dS = E 4\pi r^2$$



$$E 4\pi r^2 = \frac{Q}{\epsilon_0} \Rightarrow E = \frac{Q}{4\pi \epsilon_0 r^2}$$

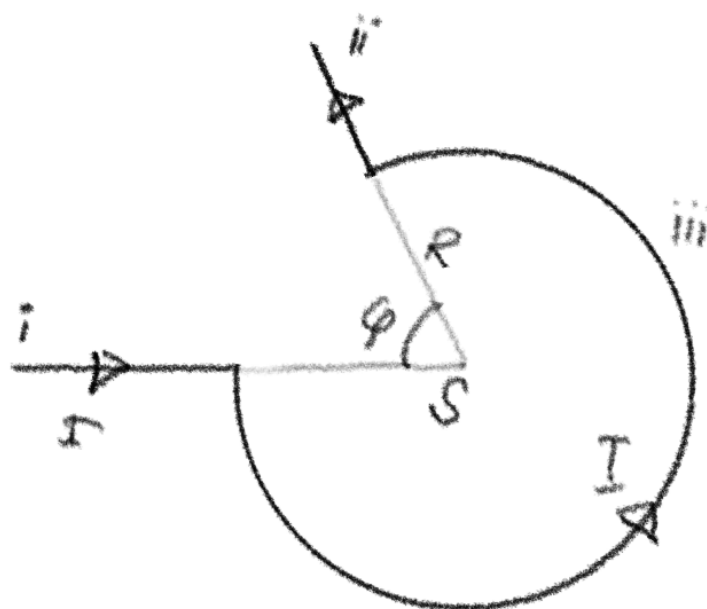
$$\varphi = -\int_{\infty}^R \frac{Q}{4\pi \epsilon_0 r^2} dr = -\frac{Q}{4\pi \epsilon_0} \left[-\frac{1}{r} \right]_{\infty}^R = \frac{Q}{4\pi \epsilon_0 R}$$

$$C = \frac{Q}{\varphi} = \frac{Q 4\pi \epsilon_0 R}{Q} = 4\pi \epsilon_0 R$$

$$\underline{\underline{R = \frac{C}{4\pi \epsilon_0}}}$$

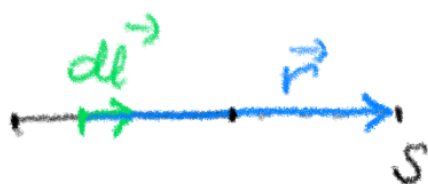
3) $\frac{I, R, \varphi}{B_j}$

$$\vec{B} = \vec{B}_i + \vec{B}_{ii} + \vec{B}_3$$

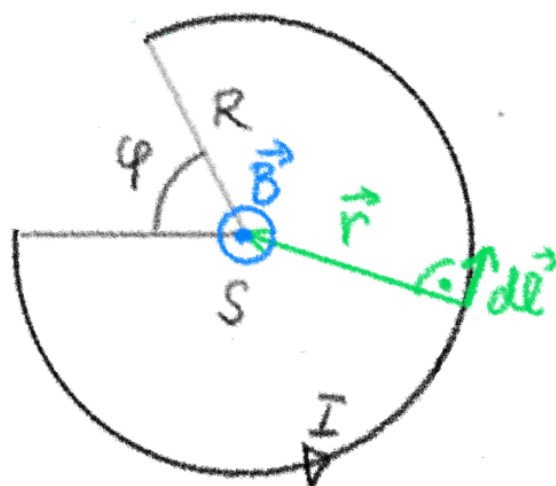


$$d\vec{B} = \frac{\mu_0}{4\pi} I \frac{d\vec{l} \times \vec{r}}{r^3}$$

i, ii) $\vec{B}_i = \vec{B}_{ii} = 0$ lebo $d\vec{l} \parallel \vec{r}$



iii) $\vec{B}_{iii}$ má smer $\neq$ náťresne $\odot$ $\vec{B}_{iii}$
 a $\vec{r} \perp d\vec{l} \Rightarrow |d\vec{l} \times \vec{r}| = r dl = R dl$



$$dB = \frac{\mu_0}{4\pi} I \frac{dl}{R^2} = \frac{\mu_0 I}{4\pi} \frac{R d\varphi}{R^2} = \frac{\mu_0 I}{4\pi R} d\varphi$$

$$B_{iii} = \frac{\mu_0 I}{4\pi R} \int_0^{2\pi-\varphi} d\varphi = \frac{\mu_0 I}{4\pi R} (2\pi-\varphi); \quad B = B_{iii}$$

$B = \frac{\mu_0 I}{4\pi R} (2\pi-\varphi)$ a smer má $\neq$ náťresne $\odot$.

4. $\frac{-e, m_e, u, B}{f}$

$$\vec{F}_m = -e \vec{v} \times \vec{B} \quad \vec{v} \perp \vec{B}$$

$$F_m = e v B = F_d$$

$$F_d = m_e \frac{v^2}{R} =$$

$$e v B = m_e \frac{v^2}{R} \Rightarrow v = \frac{e B R}{m_e} \Rightarrow \omega = \frac{e B}{m_e}$$

$$f = \frac{e B}{2\pi m_e}$$



$$v = R\omega = R2\pi f$$