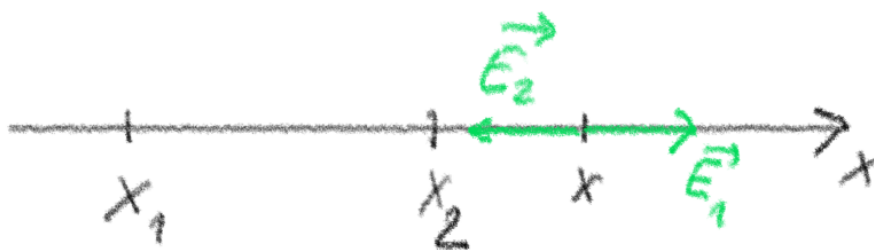


1. $x_1, q_1 > 0, x_2, q_2 < 0$

x_j



$$x \notin \langle x_1, x_2 \rangle$$

$$\vec{E}_1 + \vec{E}_2 = \vec{0}$$

$$E_{1x} = \frac{1}{4\pi\epsilon_0} \frac{q_1}{(x-x_1)^2}$$

$$E_{2x} = \frac{1}{4\pi\epsilon_0} \frac{q_2}{(x-x_2)^2}$$

$$\frac{1}{4\pi\epsilon_0} \frac{q_1}{(x-x_1)^2} + \frac{1}{4\pi\epsilon_0} \frac{q_2}{(x-x_2)^2} = 0$$

$$q_1 (x-x_2)^2 + q_2 (x-x_1)^2 = 0$$

$$q_1 (x^2 - 2xx_2 + x_2^2) + q_2 (x^2 - 2xx_1 + x_1^2) = 0$$

$$x^2(q_1 + q_2) - 2x(q_1x_2 + q_2x_1) + q_1x_2^2 + q_2x_1^2 = 0$$

$$\begin{aligned} D &= 4(q_1x_2 + q_2x_1)^2 - 4(q_1 + q_2)(q_1x_2^2 + q_2x_1^2) = \\ &= \cancel{4q_1^2x_2^2} + \cancel{4q_2^2x_1^2} + 8q_1q_2x_1x_2 - \cancel{4q_1^2x_2^2} - \cancel{4q_2^2x_1^2} - \\ &\quad - 4q_1q_2x_1^2 - 4q_1q_2x_2^2 = \\ &= -4q_1q_2(x_1^2 + x_2^2 - 2x_1x_2) = -4q_1q_2(x_2 - x_1)^2 \geq 0 \\ &\quad \text{lebo } q_1q_2 < 0 \end{aligned}$$

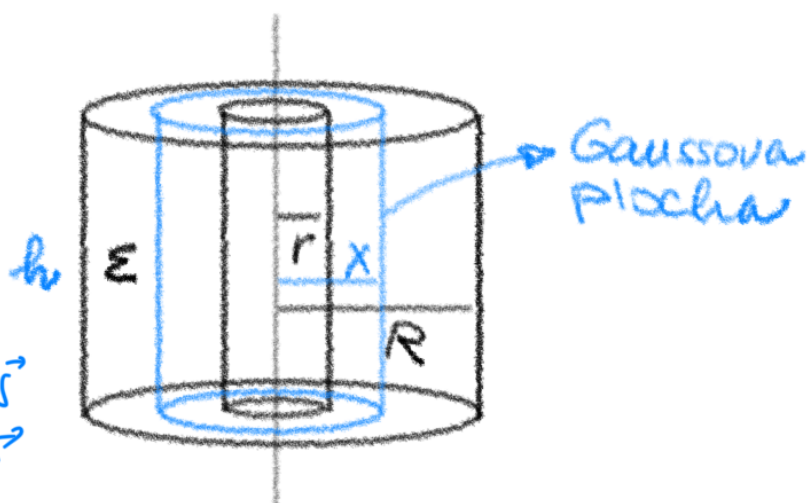
$$x_{1,2} = \frac{2(q_1x_2 + q_2x_1) \pm 2|x_2 - x_1|\sqrt{-q_1q_2}}{2(q_1 + q_2)}$$

$$x_{1,2} = \frac{q_1x_2 + q_2x_1 \pm |x_2 - x_1|\sqrt{-q_1q_2}}{q_1 + q_2}$$

2. $\frac{r, R, \epsilon}{C}$

$$\oint_S \vec{D} \cdot d\vec{S} = Q$$

$$\oint_S \vec{D} \cdot d\vec{S} = \int_{\text{Plášť}} \vec{D} \parallel d\vec{S} + \int_{\text{Podstava}} \vec{D} \perp d\vec{S} = 0$$



$$\oint_S \vec{D} \cdot d\vec{S} = \int_{\text{Plášť}} \vec{D} \cdot d\vec{S} = \int_{\text{Plášť}} D dS = D \int_{\text{Plášť}} dS = D 2\pi x h$$

$$D 2\pi x h = Q \Rightarrow D = \frac{Q}{2\pi x h}$$

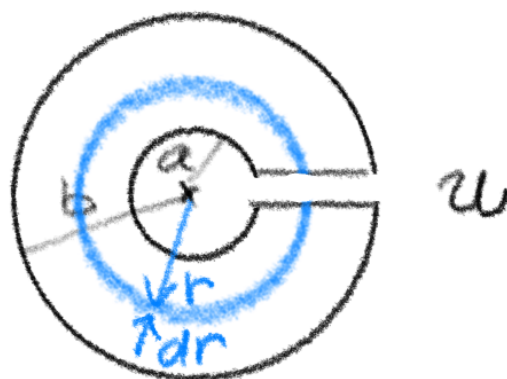
$$D = \epsilon E \Rightarrow E = \frac{D}{\epsilon} = \frac{Q}{2\pi \epsilon x h}$$

$$U = \int_r^R E dx = \int_r^R \frac{Q dx}{2\pi \epsilon x h} = \frac{Q}{2\pi \epsilon h} \left[\ln x \right]_r^R = \frac{Q}{2\pi \epsilon h} \ln R/r$$

$$C = \frac{Q}{U} = \frac{2\pi \epsilon h}{\ln R/r} \quad c = \frac{C}{a} = \frac{2\pi \epsilon}{h \ln R/r}$$

3. $\frac{a, b, h, \epsilon, U}{I, P}$

$$I = \frac{U}{R} = U G \quad P = \frac{U^2}{R} = G U^2$$



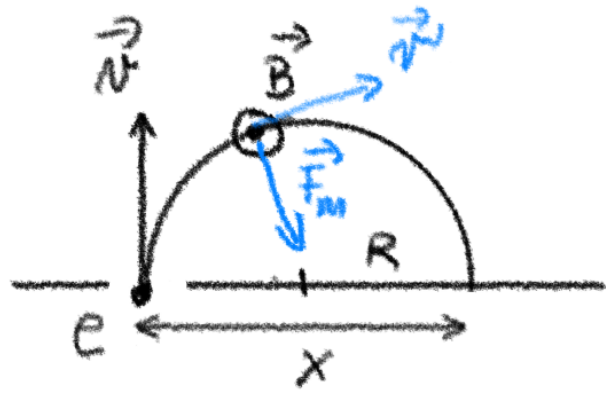
$$dG = \frac{1}{\epsilon} \frac{h dr}{2\pi r}$$

$$G = \frac{h}{2\pi \epsilon} \int_a^b \frac{dr}{r} = \frac{h}{2\pi \epsilon} \ln b/a$$

$$I = \frac{h U}{2\pi \epsilon} \ln b/a$$

$$P = \frac{h U^2}{2\pi \epsilon} \ln b/a$$

4. $\frac{U, e, \vec{B}, x}{m_p}$



$$F_m = e v B$$

$$F_d = m_p \frac{v^2}{R}$$

$$R = \frac{x}{2}$$

$$F_m = F_d$$

$$e \cdot \sqrt{\frac{2eU}{m_p}} B = \frac{2eU}{x/2}$$

$$B \sqrt{\frac{2eU}{m_p}} = \frac{4U}{x}$$

$$B^2 \frac{2eU}{m_p} = \frac{16U^2}{x^2}$$

$$m_p = \frac{e B^2 x^2}{8U}$$

$$\Delta E_k + \Delta E_p = 0$$

$$\frac{1}{2} m_p v^2 - eU = 0$$

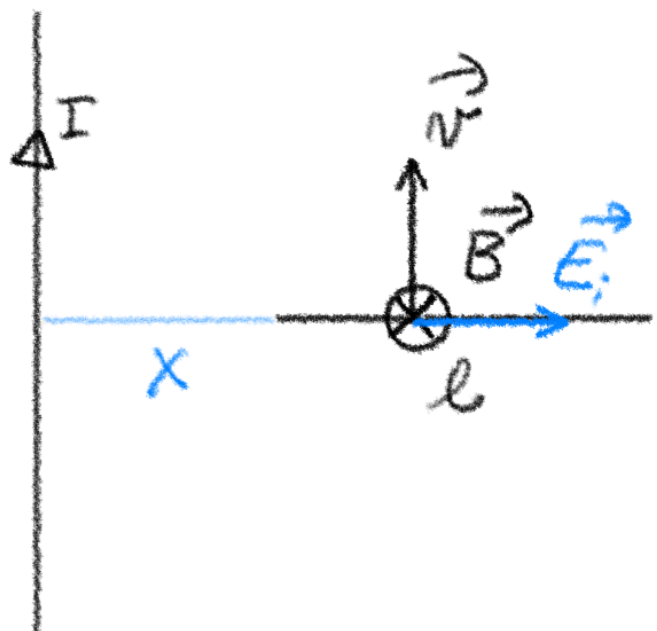
$$v^2 = \frac{2eU}{m_p}$$

$$v = \sqrt{\frac{2eU}{m_p}}$$

5. $\frac{I, x, l, \vec{r}}{U_i}$

$$B = \frac{\mu_0 I}{2\pi r}$$

$$\vec{E}_i = \vec{v} \times \vec{B}$$



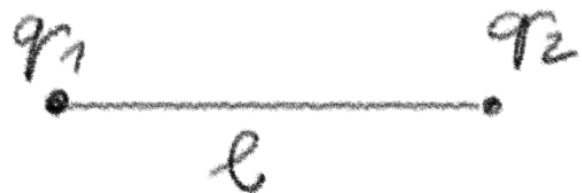
$$U_i = \int_l \vec{E}_i \cdot d\vec{r} = \int_l (\vec{v} \times \vec{B}) \cdot d\vec{r} =$$

$$\begin{aligned}
 &= \int_x^{x+l} v B dr = v \int_x^{x+l} \frac{\mu_0 I}{2\pi r} dr = \\
 &= \frac{\mu_0}{2\pi} I v \int_x^{x+l} \frac{dr}{r} = \frac{\mu_0 I v}{2\pi} [\ln]_x^{x+l}
 \end{aligned}$$

$$U_1 = \frac{\mu_0 I v}{2\pi} \ln(1 + l/x)$$

6. q_1, q_2, m, l

$$v_1, v_2$$



$$E_{p1} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{l} \quad E_{k1} = 0$$

$$E_{p2} = 0 \quad E_{k2} = \frac{1}{2} m (v_1^2 + v_2^2)$$

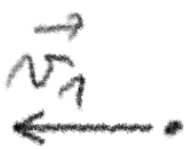
Zákon zachování energie:

$$E_{p1} + E_{k1} = E_{p2} + E_{k2}$$

$$\frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{l} = \frac{1}{2} m (v_1^2 + v_2^2)$$

Zákon zachování hybnosti:

$$0 = m \vec{v}_1 + m \vec{v}_2$$



q_1

$$\vec{v}_1 = -v_1 \vec{i}$$



q_2

$$\vec{v}_2 = v_2 \vec{i}$$

$$0 = m(-v_1 \vec{r}) + m v_2 \vec{r}$$

$$m(v_2 - v_1) = 0 \Rightarrow v_1 = v_2 = v$$

$$\frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{\ell} = \frac{1}{2} m 2v^2 = mv^2$$

$$v = \sqrt{\frac{q_1 q_2}{4\pi\epsilon_0 m \ell}}$$